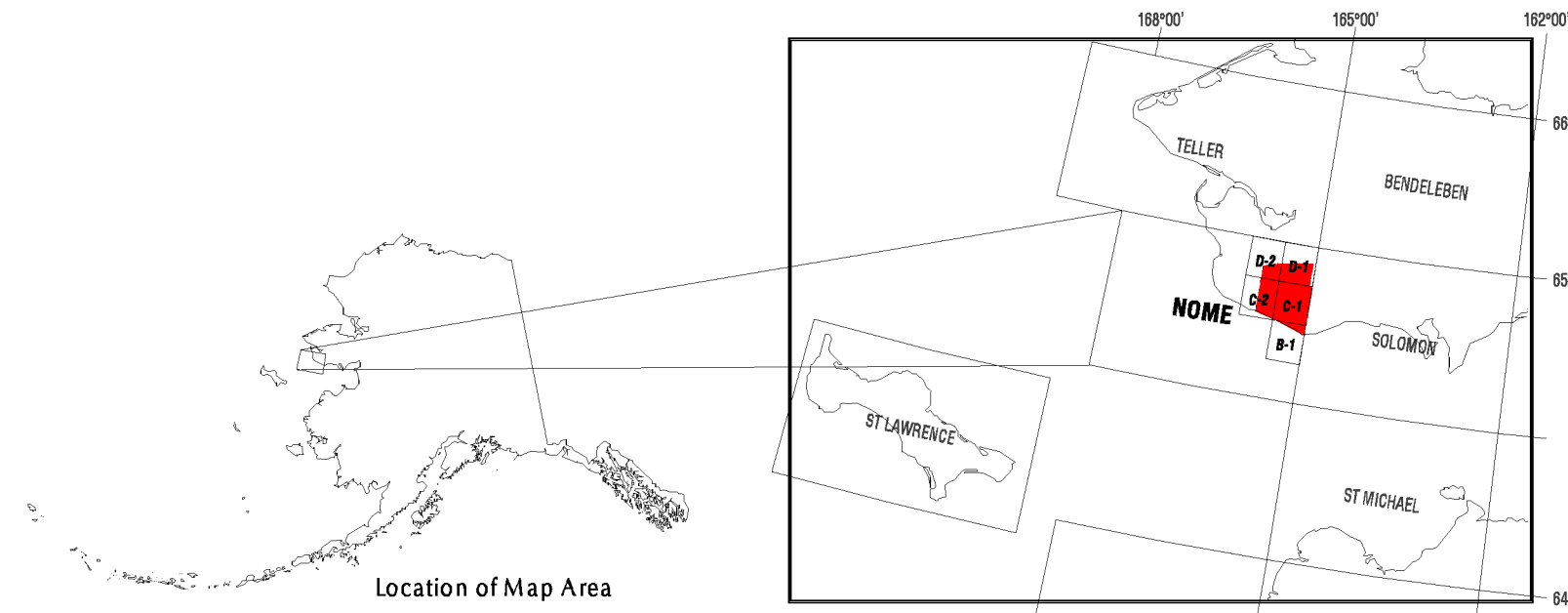


DESCRIPTIVE NOTES

Geophysical data were acquired with a DIGHEM Electromagnetic (EM) system, a Scintrex cesium CS2 magnetometer, and a Herz VLF system installed in an AS-50B-1 Squirrel helicopter. In addition, the survey recorded data from a radar altimeter, GPS navigation system, 50/60 Hz monitors, and video camera. Flights were performed at a mean terrain clearance of 200 feet along survey flight lines with a spacing of a quarter of a mile. The lines were flown perpendicular to the flight lines at intervals of approximately three miles.

A Serceal Real-Time Differential Global Positioning System (RT-DGPS) was used for both navigation and flight path recovery. The helicopter position was derived every 0.5 seconds using both real-time and p



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Division of Geological and Geophysical Surveys
Geologic Data Modeling System

Map projection: Universal Transverse Mercator

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